

Onsager's conjecture

[In these lectures we consider the following system of PDE] Incompressible Euler Equations:

$$(E) \begin{cases} \partial_t v + \operatorname{div}(v \otimes v) + \nabla p = 0 & \text{in } \mathbb{T}^3 \times [0, T] \\ \operatorname{div} v = 0 & \text{in } \mathbb{T}^3 \times [0, T] \end{cases}$$

where $v: \mathbb{T}^3 \times [0, T] \rightarrow \mathbb{R}^3$ velocity, $p: \mathbb{T}^3 \times [0, T] \rightarrow \mathbb{R}$ pressure

[Motion of an ideal, incompressible fluid, periodic boundary conditions. (incompressible preserves area)]

Classical solutions ($v, p \in C^1(\mathbb{T}^3 \times [0, T])$)

Theorem: Let $v_0 \in C^1(\mathbb{T}^3)$, $\operatorname{div} v_0 = 0$.

Then $\exists T = T(\|v_0\|_{C^1}) > 0$ and $(v, p): \mathbb{T}^3 \times [0, T] \rightarrow \mathbb{R}^3 \times \mathbb{R}$ classical solution of (E) with $v(0, \cdot) = v_0$.

[Global in time solutions: long-standing difficult open problem.]

Conservation of the energy

$$\text{Let } E(t) = \int_{\mathbb{T}^3} |v(x, t)|^2 dx \quad \forall t \in [0, T]$$

$$\frac{d}{dt} E(t) = \int_{\mathbb{T}^3} v \cdot \partial_t v \, dx = \int_{\mathbb{T}^3} -v \operatorname{div}(v \otimes v) - \int_{\mathbb{T}^3} v \nabla p \cdot p$$

$$= - \int_{\mathbb{T}^3} v_i v_j \partial_j v_i - \int_{\mathbb{T}^3} \operatorname{div} v \cdot p$$

$$= \int_{\mathbb{T}^3} \partial_j v_i (v_j v_i) + v_i^2 \partial_j v_j$$

$$= 0$$

Formally, the Euler equations can be obtained as the inviscid limit of the ^{incompressible} Navier-Stokes equations

$$\begin{cases} \partial_t v + \operatorname{div}(v \otimes v) + \nabla p = \nu \Delta v \\ \operatorname{div} v = 0 \end{cases}$$

[ν is the viscosity]

For N.-S.

$$\frac{d}{dt} E(t) = -\nu \int |\nabla v|^2 < 0 \Rightarrow \text{dissipation.}$$

What is observed in experiments is that, for arbitrarily small viscosity, dissipation persists. Correspondingly then, the L^2 -norm of the gradient would ^{have} to blow-up.

Onsager '49 conjectured that there may exist solutions of the Euler equations, non-classical, which dissipate the total kinetic energy.

* Def: We say $v \in C^\alpha$, $\alpha \in (0, 1)$ if $\exists C > 0$ s.t.
 $\forall x, y \in \mathbb{T}^3, \forall t \in [0, T]$

$$|v(x, t) - v(y, t)| \leq C |x - y|^\alpha$$

Conjecture: If $v \in C^\alpha$ ^{weak} solution of (E) and

(1) $\alpha > \frac{1}{3}$, then energy must be conserved;

(2) $\alpha < \frac{1}{3}$, then energy might be dissipated.

* Def. (weak solution of (E)) A function $v \in L^\infty([0, T]; L^2(\mathbb{T}^3))$ is a weak solution of (E) if, $\forall \psi \in C_c^\infty(\mathbb{T}^3 \times (0, T))$, $\operatorname{div} \psi = 0$ and $\forall \varphi \in C_c^\infty(\mathbb{T}^3 \times (0, T))$,

$$\int_0^T \int_{\mathbb{T}^3} v \partial_t \psi + (v \otimes v) : \nabla \psi = 0$$

$$\int_0^T \int_{\mathbb{T}^3} v \cdot \nabla \varphi = 0 \quad \square$$

Part (1) (Constantin, E, Titi 1994)

Theorem: Let $v \in C^\alpha$ be a weak solution of (E).

If $\alpha > \frac{1}{3}$, then $E(t) = E(0) \quad \forall t \in [0, T]$.

Proof: Let $\{\varphi_\varepsilon\}$ be a family of standard mollification kernels $\text{on } \mathbb{T}^3$. Let $v_\varepsilon = v * \varphi_\varepsilon$. $v_\varepsilon \in C^\infty(\mathbb{T}^3)$

29. for v_ε

$$\frac{d}{dt} \int |v_\varepsilon|^2 = \int v_\varepsilon \partial_t v_\varepsilon = \int (v \otimes v)_\varepsilon : \nabla v_\varepsilon = \int \text{Tr}((v \otimes v)_\varepsilon \nabla v_\varepsilon)$$

$$\int |v_\varepsilon(x, t)|^2 dx - \int |v_\varepsilon(x, 0)|^2 dx = \int_0^t \int_{\mathbb{T}^3} \text{Tr}((v \otimes v)_\varepsilon \nabla v_\varepsilon) dx dt$$

Aim: To show $\int_0^t \int_{\mathbb{T}^3} \text{Tr}((v \otimes v)_\varepsilon \nabla v_\varepsilon) dx dt \xrightarrow{\varepsilon \rightarrow 0} 0$

$$\int_{\mathbb{T}^3} \text{Tr}(v_\varepsilon \otimes v_\varepsilon \nabla v_\varepsilon) = 0.$$

$$(v \otimes v)_\varepsilon = v_\varepsilon \otimes v_\varepsilon + r_\varepsilon(v, v) - (v - v_\varepsilon) \otimes (v - v_\varepsilon) \quad \leftarrow \text{disapp}$$

where $r_\varepsilon(v, v) = \int \varphi_\varepsilon(y) [(v(x-y) - v(x)) \otimes (v(x-y) - v(x))] dy$

$$\|r_\varepsilon(v, v)\|_{L^{3/2}} \leq C \left(\int_{B_\varepsilon(0)} \|v(\cdot - y) - v(\cdot)\|_{L^{3/2}}^2 dy \right)^{1/2} \leq C \varepsilon^{2\alpha} \|v\|_{C^\alpha}^2$$

$$\|(v - v_\varepsilon) \otimes (v - v_\varepsilon)\|_{L^{3/2}} \leq C \varepsilon^{2\alpha} \|v\|_{C^\alpha}^2, \quad \|\nabla v_\varepsilon\|_{L^3} \leq C \varepsilon^{\alpha-1} \|v\|_{C^\alpha}$$

$$\left| \int |v_\varepsilon(x, t)|^2 dx - \int |v_\varepsilon(x, 0)|^2 dx \right| \leq C \int_0^t \left\{ \|r_\varepsilon\|_{L^{3/2}} \|\nabla v_\varepsilon\|_{L^3} + \|(v - v_\varepsilon) \otimes (v - v_\varepsilon)\|_{L^{3/2}} \|\nabla v_\varepsilon\|_{L^3} \right\} dt \leq C \varepsilon^{\alpha-1/3} \int_0^t \|v_\varepsilon\|_{C^\alpha}^3 dt \rightarrow 0$$

if $\alpha > \frac{1}{3}$.

Part 2

- Scheffer, Shnirelman '90s

Construction of compactly supported L^2 (and then L^∞) weak solutions in 2d and 3d. ($\mathbb{T}^3 \leftrightarrow D \subset \mathbb{R}^d$)

- De Lellis and Székelyhidi '07

\exists many L^∞ compactly supported solutions in arbitrary dimensions ($\mathbb{T}^3 \leftrightarrow D$)

- De Lellis and Székelyhidi '10

Given $e \in C([0, T]; \mathbb{R}^+)$, there exist ∞ many L^∞ compactly supported solutions of (E) with total kinetic energy e . ($\mathbb{T}^3 \leftrightarrow D$)

- De Lellis and Székelyhidi '12

Given $e \in C^\infty([0, T]; \mathbb{R}^+)$, there exist ∞ many C^0 solutions of (E) with $\int |v|^2 dt = e(t)$.

- De Lellis and Székelyhidi '12

C^α , $\alpha < \frac{1}{10}$

- Isett '14

\exists of compactly supported solutions in

C^α , $\alpha < \frac{1}{5}$ (prescribed total kinetic energy (by Buckmaster, De Lellis, Isett, Székelyhidi))

- Daneri, Székelyhidi '16

Non-uniqueness of C^α solutions, $\alpha < \frac{1}{5}$ and density in L^2 of non-uniqueness initial data

- Isett '16. \exists of compactly supp. sol. in C^α , $\alpha < \frac{1}{5}$ (pres. tot. Kin. en. by Buck, De L., Sz., and Vicol '17)

AIM: To give overview of the proof of [BDSV] \rightarrow

Strategy of the proof (starting from De Lellis and Székelyhidi '07)

CONVEX INTEGRATION

- 1) Start from a SUBSOLUTION of the problem
- 2) Add iteratively a sequence of nonlinear perturbations to the flow so that at each step one obtains still a subsolution, but with a smaller gap from being a solution.
- 3) At each step obtain estimates on the flow that imply convergence of the subsolutions to a solution of the problem in the desired topology.

[Convex integration for the first time apply by Nash for the problem of isometric 1d isometric immersions in \mathbb{R}^3 immersions. Let us look at a toy example ...]

look for $f \in C^1([0,1]; \mathbb{R}^3)$ s.t. $|f'| = 1$ and $f([0,1]) \subset B_{\mathbb{R}^3}(0)$

Idea: obtain f as the C^1 -limit of $\{f_m\} \subset C^0([0,1]; B_{\mathbb{R}^3}(0))$ with

$$1 - \delta_m < |f'_m|^2 < 1, \quad \{\delta_m\} \subset (0,1), \quad \delta_m \searrow 0$$

Subsolutions

$$f_{m+1}(t) = f_m(t) + \frac{\sqrt{\delta_m - \delta_{m+1}}}{\sqrt{2} \lambda_{m+1}} \cos(\lambda_{m+1} t) \vec{m} + \frac{\sqrt{\delta_m - \delta_{m+1}}}{\sqrt{2} \lambda_{m+1}} \sin(\lambda_{m+1} t) \vec{b}$$

Picture \rightarrow

where $\lambda_{m+1} \gg 1$, and $\frac{f'_m}{|f'_m|}, \vec{b}, \vec{m}$ regularised Frenet frame

$$|f'_{m+1} - f'_m| \sim \frac{\sqrt{\delta_m}}{\lambda_{m+1}}, \quad |f'_{m-1} - f'_m| \sim \sqrt{\delta_m}$$

$$|f'_{m+1}|^2 = |f'_m|^2 + \delta_m - \delta_{m+1} + o(\lambda_{m+1}^{-1}).$$

Solutions for the Euler equations

Euler-Reynolds system

$$\begin{cases} \partial_t v + \operatorname{div}(v \otimes v) + \nabla p = -\operatorname{div} R \\ \operatorname{div} v = 0 \end{cases}$$

where $R \in S_{>0}^{3 \times 3}$.

Typical equation for averages of (E), which is used in turbulence theory (there $R_0 > 0$)
We ask also that $R = \beta(t) \operatorname{Id} + \tilde{R}$.
Moreover

$$\int_{\mathbb{T}^3} |v(x,t)|^2 dx < \epsilon(t) \quad \forall t \in [0, T]$$

Let $v_q = v$, $v_{q+1} = v + w$ and let us try to make an Ansatz on the perturbations.

$$\|v_q - v_{q-1}\|_0 \leq \delta_q^{1/2}$$

$$\|v_q\|_1 \leq \delta_q^{1/2} \lambda_q$$

$$\|v_q - v_{q-1}\|_\beta \leq \delta_q^{1/2(1-\beta)} \delta_q^{1/2\beta} \lambda_q^\beta = \delta_q^{1/2} \lambda_q^\beta$$

$\delta_q = \lambda_q^{-2\beta}$, $\forall \Rightarrow v_q$ converge in $C^{\beta'}$ $\forall \beta' < \beta$.

$$\left[\lambda_q = [a^{b^q}], \quad a \gg 1, \quad 1 < b < 1 + \epsilon \right]$$

Also $\|R_q\|_0$ and $\epsilon(t) - \int |v(t)|^2$ have to converge to 0.

$$\begin{aligned}
& \partial_t (v_q + w) + \operatorname{div} (v_q + w) \otimes (v_q + w) + \nabla(p_q + p) = \\
& = - \operatorname{div} \mathring{R}_{q+1} \\
& = \operatorname{div} (w \otimes w + p \operatorname{Id} - \mathring{R}_q) \quad \text{oscillation term} \\
& \quad + \partial_t w + v_q \cdot \nabla w \quad \text{transport term} \\
& \quad + w \cdot \nabla v_q \quad \text{Nash error term}
\end{aligned}$$

In first approximation

$$w(x, t) = \sum_{k \in \mathbb{N}} a_k(x, t) e^{i \lambda k \cdot x} = W(x, t, \lambda x), \quad \lambda \gg 1$$

$$W(x, t, \xi) = \sum_{k \in \mathbb{N}} a_k(x, t) e^{i k \cdot \xi}$$

Lemma: If $\operatorname{div} w = 0$, $\exists \mathring{R}_{q+1} = R(\text{o. term} + \text{t. term} + \text{N. term})$
 R elliptic operator. Moreover, $\forall m \in \mathbb{N}, \theta \in (0, 1), \exists C = C(m, \theta)$
s.t. $\forall F(x) = a(x) e^{i \lambda k \cdot x}, k \neq 0$

$$\|R(F)\|_{\theta} \leq C \left(\frac{\|a\|_0}{\lambda^{1-\theta}} + \frac{[a]_m}{\lambda^{m-\theta}} + \frac{[a]_{m+\theta}}{\lambda^m} \right)$$

$$\begin{aligned}
[(R f)^i]_j &= R^{ijk} f^k, \text{ where } R^{ijk} = -\frac{1}{2} \Delta^{-2} \partial_i \partial_j \partial_k + \frac{1}{2} \Delta^{-1} \partial_k \delta_{ij} \\
&\quad - \Delta^{-1} \partial_i \delta_{jk} - \Delta^{-1} \partial_j \delta_{ik}, \text{ operator of order } -1.
\end{aligned}$$

|| So, the terms of order λ and higher in the error terms should vanish.

In particular, this gives

$$\begin{cases} \operatorname{div}_g W \otimes W = \nabla p \\ \operatorname{div}_g W = 0 \end{cases} \leftarrow \text{stationary solutions of Euler}$$

and $\int W \otimes W \, dg = f(t) \operatorname{Id} + \mathring{R}_g$

$$W \sim \delta_{g+1}^{1/2} \rightarrow \boxed{\|\mathring{R}_g\| \leq \delta_{g+1} \left(\lambda_g^{-3\theta} \right)} \quad 0 < \theta < 1$$

(Beltrami flows up to $1/2$ paper)

Mikado flows (D., Sz. 116)

Lemma: For any compact subset $\mathcal{N} \subset \subset S_+^{3 \times 3}$ there exists a smooth vector field

$$W: \mathcal{N} \times \mathbb{T}^3 \rightarrow \mathbb{R}^3$$

such that, $\forall R \in \mathcal{N}$

$$\begin{cases} \operatorname{div}_g (W(R, \xi) \otimes W(R, \xi)) = 0 \\ \operatorname{div}_g W(R, \xi) = 0 \end{cases}$$

$$\int_{\mathbb{T}^3} W(R, \xi) = 0$$

$$\int_{\mathbb{T}^3} W(R, \xi) \otimes W(R, \xi) = R$$

Lemma: \forall compact subset $N \subset S_+^{3 \times 3}$ there exists $\lambda_0 \geq 1$ and smooth functions $\Gamma_\kappa \in C^\infty(N; [0, 1]) \forall \kappa \in \mathbb{Z}^3$ with $|\kappa| \leq \lambda_0$ such that

$$R = \sum_{\kappa \in \mathbb{Z}^3, |\kappa| \leq \lambda_0} \Gamma_\kappa^2(R) \kappa \otimes \kappa, \quad \forall R \in N.$$

Then we take

$$W(R, \xi) = \sum_{\kappa \in \mathbb{Z}^3, |\kappa| \leq \lambda_0} \Gamma_\kappa(R) \psi_\kappa(\xi) \kappa$$

where $\psi_\kappa(\xi) = g_\kappa(\text{dist}(\xi, \ell_{\kappa, p_\kappa}))$ with $g_\kappa \in C_c^\infty(0, r_\kappa)$

$r_\kappa > 0$ and ℓ_{κ, p_κ} is the \mathbb{T}^3 -periodic extension of the line $\{p_\kappa + t\kappa : t \in \mathbb{R}\}$ passing through p_κ in direction κ . One chooses p_κ and $r_\kappa > 0$ so that

$$\text{supp } \psi_i \cap \text{supp } \psi_j = \emptyset \quad \forall i \neq j.$$

and g_κ so that $\int \psi_\kappa^2(\xi) d\xi = 1 \quad \forall \kappa$

$$\begin{aligned} \text{Then } \int W \otimes W d\xi &= \sum_{\kappa} \int \Gamma_\kappa^2(R) \psi_\kappa^2(\xi) \kappa \otimes \kappa \\ &= \sum_{\kappa} \Gamma_\kappa^2(R) \kappa \otimes \kappa = R. \end{aligned}$$

Transport error

$$\partial_t w + v_q \cdot \nabla w$$

← what happens for the previous on sat $t \rightarrow 1/\lambda_0$

We take phase of the form

$$\sum_{j,k} \chi_{jk} e^{i \lambda_{jk} \cdot \Phi_j(x,t)} a_{jk}(x,t)$$

where

$$\begin{cases} \partial_t \Phi_j + v_q \cdot \nabla \Phi_j = 0 \\ \Phi_j(x, t_j) = x \end{cases}$$

$$|t_j - t_{j-1}| \leq \frac{1}{2} [v_q]^{-2}$$



$$\left(\|\nabla \Phi_j - Id\|_0 \leq |t_j - t_{j-1}| [v]_1 \right) \leftarrow \begin{matrix} \text{estimates} \\ \|\cdot\|_w \end{matrix}$$

cut-off necessary in order to have good estimates for the transport equation and stationary lemma.

Nash error $\|dw^{-1}(w \cdot \nabla v_q)\|_0 \sim \frac{\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q}{\lambda_{q+1}}$

$$\frac{\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q}{\lambda_{q+1}} \in \delta_{q+2} (\lambda_{q+1}^{-3})$$

$$\rightarrow [\lambda_q = [a^{b^q}]]$$

$$b^q (-\alpha_0 - \alpha + 1 - b) \leq b^q (-2\alpha b^2)$$

$$\alpha (2b^2 - b - 1) + 1 - b < 0$$

$$\alpha < \frac{b-1}{(b-1)(2b+1)} = \frac{1}{2b+1} < \left(\frac{1}{3}\right)$$

Energy estimate What is $f(t)$?

$$\int_{\mathbb{T}^3} |v_q + w|^2 = \int_{\mathbb{T}^3} |v_q|^2 + \int_{\mathbb{T}^3} |w|^2 + 2 \int_{\mathbb{T}^3} v_q \cdot w$$

$$\sim \int_{\mathbb{T}^3} \frac{|v|^2}{q} + \int_{\mathbb{T}^3} 3f(t)$$

$$= \int_{\mathbb{T}^3} \frac{|v|^2}{q} + 3(2\pi)^3 f(t)$$

In order to reduce the gap, choose

$$f(t) = \frac{1}{3(2\pi)^3} \left(e(t) - \int_{\mathbb{T}^3} \frac{|v_q|^2}{q} - \delta_{q+2} e(t) \right)$$

$$\left(\begin{aligned} e(t) - \int_{\mathbb{T}^3} \frac{|v_q|^2}{q} &\sim \delta_{q+1}, \\ e(t) - \int_{\mathbb{T}^3} \frac{|v_{q+1}|^2}{q} &\sim \delta_{q+2} \end{aligned} \right)$$

∴

→ Mollification (in order not to have loss of derivatives)

We mollify v_q at length scale l , for some fixed $l = l(q)$.

$$v_e := v_q * \psi_l \quad p_e = p_q * \psi_l$$

$$\begin{cases} \partial_t v_e + \operatorname{div}(v_e \otimes v_e) + \nabla p_e = \operatorname{div} \dot{r}_e \\ \operatorname{div} v_e = 0 \end{cases}$$

where

$$\dot{r}_e = \dot{r}_q * \psi_l + (v_q \otimes v_q) * \psi_l - v_e \otimes v_e$$

Proposition: Let $\|v_e\|_{N+1} \lesssim \|v_q\|_1 e^{-N}$, $\|v_q - v_e\|_0 \leq \|v_q\|_1 l$

$$l = \frac{\delta_{q+1}^{1/2}}{\delta_q^{1/2} \lambda_q^{1+\theta/2}}, \quad \theta \in (0, 1) \text{ small}$$

Then

$$\begin{aligned} \|v_e - v_q\|_0 &\lesssim \delta_{q+1}^{1/2} \lambda_q^{-\theta} \\ \|v_e\|_{N+1} &\lesssim \delta_q^{1/2} \lambda_q e^{-N} \\ \|\dot{r}_e\|_{N+\theta} &\lesssim \delta_{q+1} e^{-N+\theta} \end{aligned}$$

$$\left| \int |v_q|^2 - |v_e|^2 \right| \lesssim \delta_{q+1} e^\theta$$

Proof: $\|v_e - v_q\|_0 \leq \|v_e\|_1 l \lesssim \delta_q^{1/2} \lambda_q l \lesssim \delta_{q+1}^{1/2} \lambda_q^{-\theta}$

Problem in the Ansatz from Transport Error

$$X_i W_i + X_j W_j \quad \text{for } t \text{ s.t. } X_i(t), X_j(t) \neq 0.$$

$$X_i X_j W_i \otimes W_j.$$

Gluing (Isett 16) Aim is to produce a new \bar{v}_q , close to v_e (and then to v_q) whose associated Reynolds stress has support in pairwise disjoint temporal regions of length τ_q in time, where τ_q

$$\tau_q = \frac{\ell^{2\theta}}{\delta_q^{1/2} \lambda_q} \ll [v_e]^{-2}.$$

For any $n \in \mathbb{Z}$, let

$$t_n = n \tau_q, \quad I_n = [t_n + \frac{1}{3} \tau_q, t_n + \frac{2}{3} \tau_q] \cap [0, T]$$

$$J_n = (t_n - \frac{1}{3} \tau_q, t_n + \frac{1}{3} \tau_q) \cap [0, T]$$

We want to build $(\bar{v}_q, \bar{p}_q, \bar{R}_q)$ so that

$$\text{supp } \bar{R}_q \subset \bigcup_{n \in \mathbb{N}} I_n \times \mathbb{T}^3.$$

← general idea

For each n , let $t_n = n \tau_q$ and consider smooth solutions of the Euler equations

$$\begin{cases} \partial_t v_n + \text{div}(v_n \otimes v_n) + \nabla p_n = 0 \\ \text{div } v_n = 0 \\ v_n(\cdot, t_n) = v_e(\cdot, t_n) \end{cases}$$

defined over their maximal interval of existence.

From the classical results, we recall the following

Proposition: $\forall \alpha > 0 \exists c = c(\alpha) > 0$ with the following property.

Given any $v_0 \in C^\infty$ and $T \leq c \|v_0\|_{N+\alpha}^{-2}$, there exists a unique solution $v: \mathbb{T}^3 \times [-T, T] \rightarrow \mathbb{R}^3$ to ~~the~~ (E) s.t. $v(\cdot, 0) = v_0$. Moreover, v obeys the bounds

$$\|v\|_{N+\alpha} \lesssim \|v_0\|_{N+\alpha}$$

Apply now Proposition to $v_0 = v_e(-, t_m) \Rightarrow v_m = v$.

Now, let us define a partition of unity $\{\chi_m\}_{m \in \mathbb{N}}$ with the following properties:

$$\bullet \sum_m \chi_m \equiv 1 \quad \text{on } [0, T]$$

$$\bullet \text{supp } \chi_m \cap \text{supp } \chi_{m+2} = \emptyset$$

and moreover

$$\text{supp } \chi_m \subset (t_m - \frac{2}{3}\tau_q, t_m + \frac{2}{3}\tau_q)$$

$$\chi_m(t) = 1 \quad \text{for } t \in I_m$$

$$\bullet \forall m, N$$

$$\|\partial_t^N \chi_m\| \leq \tau_q^{-N}$$

Define then

$$\bar{v}_q = \sum_m \chi_m v_m$$

$$\bar{p}_q^{(1)} = \sum_m \chi_m p_m$$

If $t \in I_m$ then $X_m + X_{m+1} = 1$ and $X_j = 0$ for $j \neq m, m+1$.

On I_m

$$\bar{v}_q = X_m v_m + (1 - X_m) v_{m+1}$$

$$\bar{p}_q^{(1)} = X_m p_m + (1 - X_m) p_{m+1}$$

and

$$\begin{aligned} \partial_t \bar{v}_q + \operatorname{div}(\bar{v}_q \otimes \bar{v}_q) + \nabla \bar{p}_q^{(1)} &= X_m \partial_t v_m + (1 - X_m) \partial_t v_{m+1} \\ &\quad + \partial_t X_m (v_m - v_{m+1}) + \operatorname{div}(X_m^2 v_m \otimes v_m + \\ &\quad + (1 - X_m)^2 v_{m+1} \otimes v_{m+1}) \\ &\quad + X_m (1 - X_m) \operatorname{div}(v_m \otimes v_{m+1} + v_{m+1} \otimes v_m) \\ &\quad + X_m \nabla p_m + (1 - X_m) \nabla p_{m+1} \\ &= \partial_t X_m (v_m - v_{m+1}) \\ &\quad - X_m (1 - X_m) \operatorname{div}((v_m - v_{m+1}) \otimes (v_m - v_{m+1})) \end{aligned}$$

On J_m , $X_m = 1$ and $X_j = 0 \ \forall j \neq m$

then

$$\bar{v}_q = v_m \quad \bar{p}_q^{(1)} = p_m$$

and

$$\partial_t \bar{v}_q + \operatorname{div}(\bar{v}_q \otimes \bar{v}_q) + \nabla \bar{p}_q^{(1)} = 0$$

Then, one defines

$$\overset{\circ}{R}_q = \partial_t X_m (v_m - v_{m+1}) - X_m (1 - X_m) (v_m - v_{m+1}) \otimes (v_m - v_{m+1})$$

$$\bar{p}_q^{(2)} = +X_m (1 - X_m) |v_m - v_{m+1}|^2$$

for $t \in I_m$ and $\overset{\circ}{R}_q = 0$, $\bar{p}_q^{(2)} = 0$ for $t \notin \bigcup_m I_m$, $\bar{p}_q = \bar{p}_q^{(1)} + \bar{p}_q^{(2)}$

Then, $\overset{\circ}{R}_q$ is a smooth ~~and~~ symmetric and traceless matrix s-t.

$$\begin{cases} \partial_t \bar{v}_q + \operatorname{div}(\bar{v}_q \otimes \bar{v}_q) + \nabla \bar{p}_q = \operatorname{div} \overset{\circ}{R}_q \\ \operatorname{div} \bar{v}_q = 0 \end{cases} \text{ on } \mathbb{T}^3 \times [0, T].$$

One can show that the following estimates hold for $(\bar{v}_q, \overset{\circ}{R}_q)$ as well:

$$\|\bar{v}_q - v_{e,0}\|_{\infty} \lesssim \delta_{q+1}^{1/2} e^{\theta}$$

$$\|\bar{v}_q\|_{1+N} \lesssim \delta_q^{1/2} \lambda_q e^{-N}$$

$$\|\overset{\circ}{R}_q\|_{N+\alpha} \lesssim \delta_{q+1} e^{-N+\theta}$$

$$\left| \int_{\mathbb{T}^3} |\bar{v}_q|^2 - |v_e|^2 dx \right| \lesssim \delta_{q+1} e^{\theta}$$

Eq.: $\bar{v}_q - v_e = \sum_m \chi_m (v_m - v_e)$

$$\|v_m - v_e\|_{\infty} \leq ?$$

One has that

$$\begin{aligned} \partial_t (v_e - v_m) + v_e \cdot \nabla (v_e - v_m) &= (v_m - v_e) \cdot \nabla v_m \\ &\quad - \nabla (p_e - p_m) + \operatorname{div} \overset{\circ}{R}_e \end{aligned}$$

In particular, using

$$\begin{aligned} \Delta (p_e - p_m) &= \operatorname{div}(\nabla v_e (v_e - v_m)) + \\ &\quad + \operatorname{div}(\nabla v_m (v_e - v_m)) + \operatorname{div} \operatorname{div} \overset{\circ}{R}_e \end{aligned}$$

and the estimates about elliptic operators,

$$\begin{aligned} \|\nabla (p_e - p_m)(\cdot, t)\|_{\infty} &\leq (\|v_e\|_{1+\theta} + \|v_m\|_{1+\theta}) \|v_e - v_m\|_{\infty} \\ &\quad + \|\overset{\circ}{R}_e\|_{1+\theta} \end{aligned}$$

From the classical estimates, we have that

$$\|v_m\|_{1+\theta} \leq \epsilon_q^{-1} e^\theta = \delta_q^{1/2} \lambda_q e^{-\theta}$$

We also know that $\|v_e\|_{1+\theta} \leq \delta_q^{1/2} \lambda_p e^{-\theta}$

and $\|\hat{r}_e\|_{1+\theta} \leq \delta_{q+1} e^{-1+\theta}$

Then, one has that

$$\|(\partial_t + v_e \cdot \nabla)(v_e - v_m)\|_\theta \lesssim \delta_{q+1} e^{-1+\theta} + \epsilon_q^{-1} \|v_e - v_m\|_\theta$$

then, for $1 + \frac{1}{\theta} \|v_e\|_\alpha \leq 1$ (which is the case now)

(Semi-discrete
trace lemma)

$$\|v_e - v_m\|_\theta \leq 2 \left(\|v_e - v_m\|_\theta(t_m) + \int_{t_m}^t \|(\partial_t + v_e \cdot \nabla)(v_e - v_m)\|_\alpha \right)$$

classical theorem
on solutions of
the transport eqns

$$\leq \epsilon_q \delta_{q+1} e^{-1+\theta} + \int_{t_m}^t \epsilon_q^{-1} \|v_e - v_m\|_\theta$$

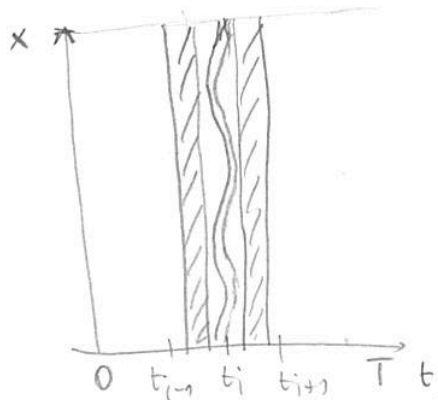
Gronwall's inequality

$$\|v_m - v_e\|_\alpha \leq \epsilon_q \delta_{q+1} e^{-1+\alpha}$$

By definition, $\delta_{q+1}^{1/2} \epsilon_q e^{-1} \leq 1$

$$\hookrightarrow \|v_m - v_e\|_\alpha \lesssim \delta_{q+1}^{1/2} e^\alpha.$$

$$v_{q+1} = \bar{v}_q + w_{q+1}$$



The support of w_{q+1} has to include

$$\bigcup_{m \in \mathcal{N}} I_m \times \mathbb{T}^3, \quad w_{q+1} = \sum_m w_m$$

In order to make the support of the w_m disjoint and at the same time reduce both the Reynolds stress and the energy gap we have to choose suitable cut-off functions η_m .

(explain why ~~the~~ $\eta_m = \eta_m(t)$ not good)

Define
$$p_q(t) := \frac{1}{3} \left(e(t) - \frac{\delta_{q+2}}{2} - \int_{\mathbb{T}^3} |\bar{v}_q|^2 dx \right)$$

$$p_{q,m}(x,t) = \frac{\eta_m^2(x,t)}{\sum_j \int \eta_j^2(y,t) dy} p_q(t)$$

$$\Phi_m \text{ s.t. } \begin{cases} (\partial_t + \bar{v}_q \cdot \nabla) \Phi_m = 0 \\ \Phi_m(x, t_m) = x \end{cases}$$

$$R_{q,m} := p_{q,m} \text{Id} - \eta_m^2 \bar{R}_q$$

$$\tilde{R}_{q,m} = \frac{\nabla \Phi_m R_{q,m} (\nabla \Phi_m)^T}{p_{q,m}}$$

Thanks to $|p_q| \geq \delta_{q+2}$ and $\|\bar{R}_q\| \leq \delta_{q+1} e^\delta$

and $\|\nabla \Phi_m - \text{Id}\| \leq \frac{1}{2}$

$\Rightarrow \tilde{R}_{q,m} \in B_{1/2}(\text{Id}) \subset S_{+}^{3 \times 3}$

the principal part of the perturbation
 $(w_{qH} = w_h + w_c$ in order to be divergence free)

$$w_0 = \sum_m (\rho_{q,m}(x,t))^{1/2} (\nabla \Phi_m)^{-1} W(\tilde{\rho}_{q,m}, \lambda_{qH} \Phi_m) = \sum_m w_m.$$

Estimates for the Reynolds stress

Nash Error

$$R(w_0 \cdot \nabla \bar{v}_q) = \sum_m R\left(\rho_{q,m}(x,t)^{1/2} (\nabla \Phi_m)^{-1} W(\tilde{\rho}_{q,m}, \lambda_{qH} \Phi_m) \cdot \nabla \bar{v}_q\right)$$

$$\rho_{q,m}(x,t)^{1/2} (\nabla \Phi_m)^{-1} W(\tilde{\rho}_{q,m}, \lambda_{qH} \Phi_m) =$$

$$= \sum_{k \neq 0} \rho_{q,m}(x,t)^{1/2} a_k(\tilde{\rho}_{q,m}) (\nabla \Phi_m)^{-1} A_k e^{i\lambda_{qH} k \cdot \Phi_m}$$

$$= \sum_{k \neq 0} (\nabla \Phi_m)^{-1} b_{m,k} e^{i\lambda_{qH} k \cdot \Phi_m}$$

$$R(w_0 \cdot \nabla \bar{v}_q) = \sum_m \sum_{k \neq 0} R\left((\nabla \Phi_m)^{-1} b_{m,k} e^{i\lambda_{qH} k \cdot \Phi_m} \cdot \nabla \bar{v}_q\right)$$

$$\|R((\nabla \Phi_m)^{-1} b_{m,k} e^{i\lambda_{qH} k \cdot \Phi_m} \cdot \nabla \bar{v}_q)\|_\alpha$$

$$\lesssim \frac{\|(\nabla \Phi_m)^{-1} b_{m,k} \cdot \nabla \bar{v}_q\|_0}{\lambda_{qH}^{1-\alpha}} + \frac{\|(\nabla \Phi_m)^{-1} b_{m,k} \cdot \nabla \bar{v}_q\|_{N+\alpha}}{\lambda_{qH}^{N-\alpha}}$$

$$+ \frac{\|(\nabla \Phi_m)^{-1} b_{m,k} \cdot \nabla \bar{v}_q\|_0 \|\Phi_m\|_{N+\alpha}}{\lambda_{qH}^{N-\alpha}}$$

$$\approx \frac{\lambda_{q+1} \delta_{q+1}^{1/2} \delta_q^{1/2}}{\lambda_{q+1}^{1-\alpha} |k|^6} + \frac{\lambda_q \delta_{q+1}^{1/2} \delta_q^{1/2}}{\lambda_q^{N-\alpha} e^{N+\alpha} |k|^6}$$

$$\approx \frac{\delta_{q+1}^{1/2} \delta_q^{1/2} \lambda_q}{\lambda_{q+1}^{1-\alpha} |k|^6}$$

provided $\frac{1}{\lambda_q^{N-\alpha} e^{N+\alpha}} \leq \frac{1}{\lambda_{q+1}^{1-\alpha}}$

First choose $\alpha > 0$ small enough and then N large \Rightarrow satisfied

[equivalent to:

$$\lambda_{q+1}^{(N-1)-(N-\alpha)\beta} \geq \lambda_q^{(1-\beta+\frac{3\alpha}{2})(N+\alpha)}$$

$$b^{q+1} ((N-1) - (N-\alpha)\beta) > b^q (N+\alpha) \left(1-\beta+\frac{3\alpha}{2}\right)$$

For α small, sufficient to check $\exists N$ s.t.

$$b((N-1) - N\beta) > N(1-\beta)$$

$$\Leftrightarrow (b-1)(N-1)(1-\beta) > (1-\beta) + b\beta$$

$$b > 1 \quad \beta < \frac{1}{3} \Rightarrow \text{true if } N \text{ large enough.}$$